

Joint Energy Beamforming and Optimization for Intelligent Reflecting Surface Enhanced Communications

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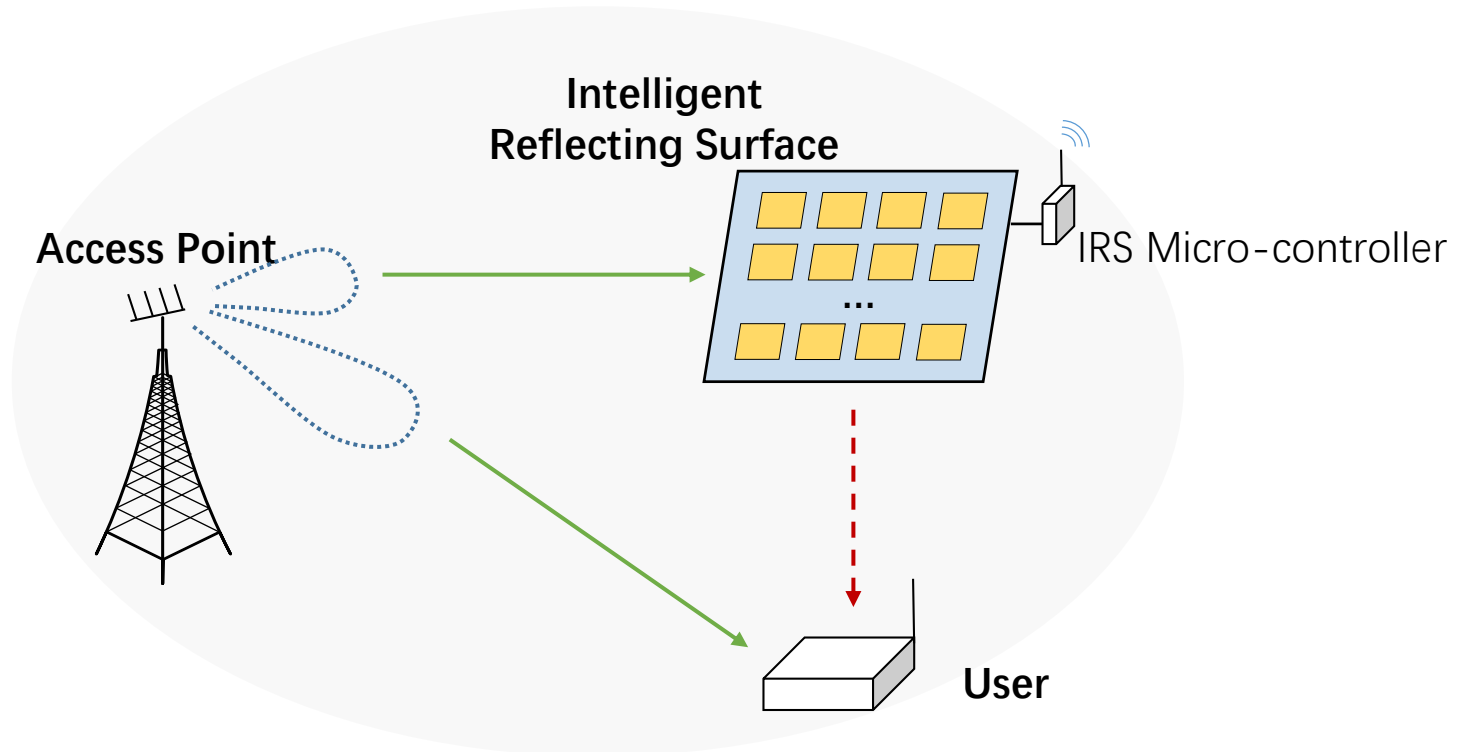
Outline

- **Introduction**
- **System Model**
- **Two-stage Approximation Algorithm**
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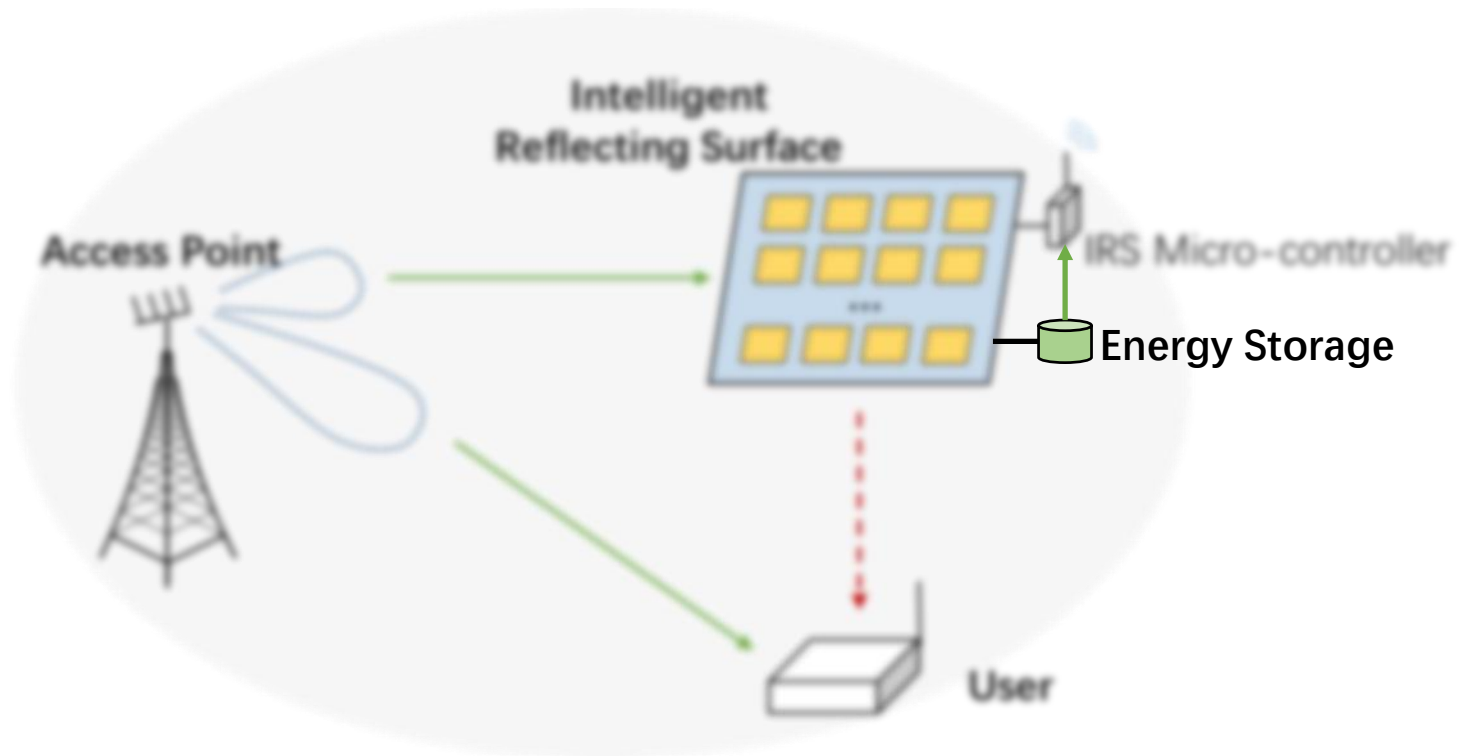
Introduction



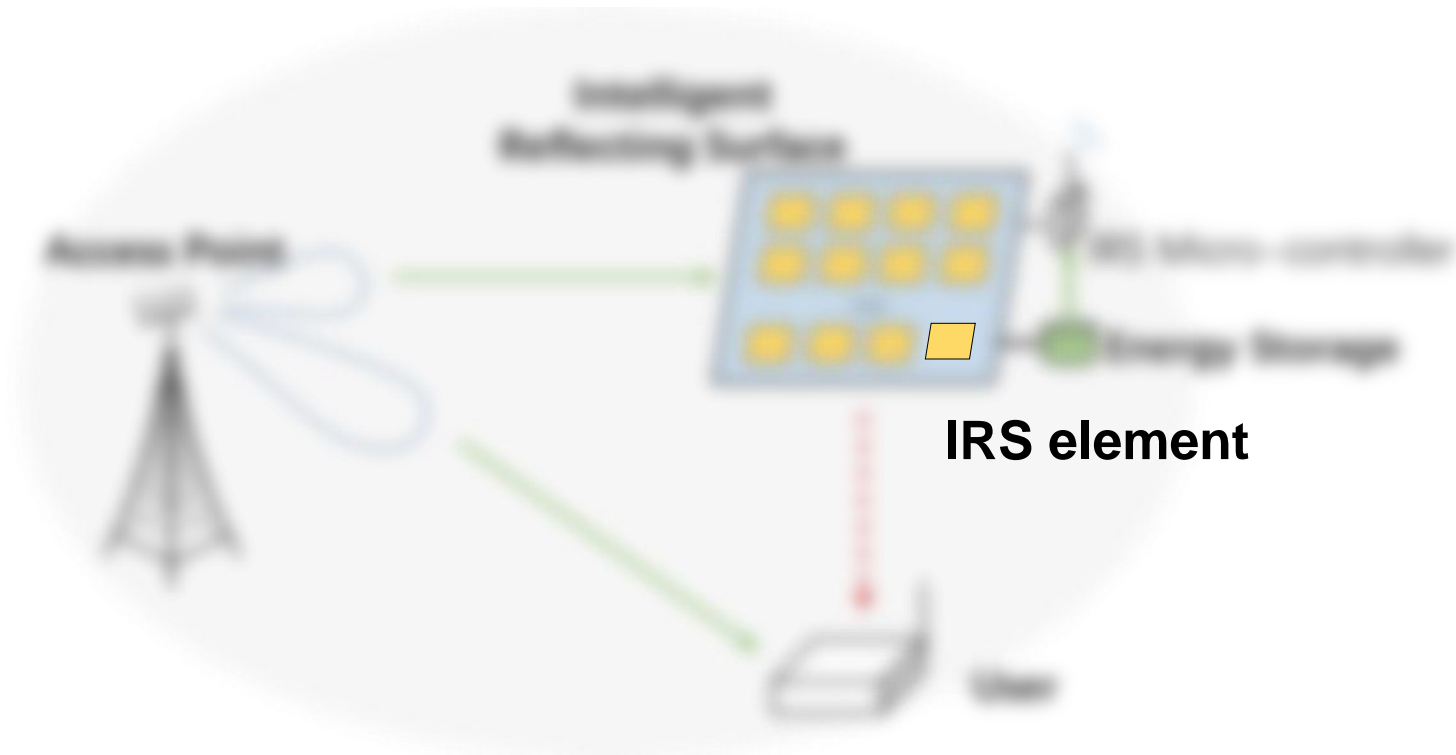
Introduction



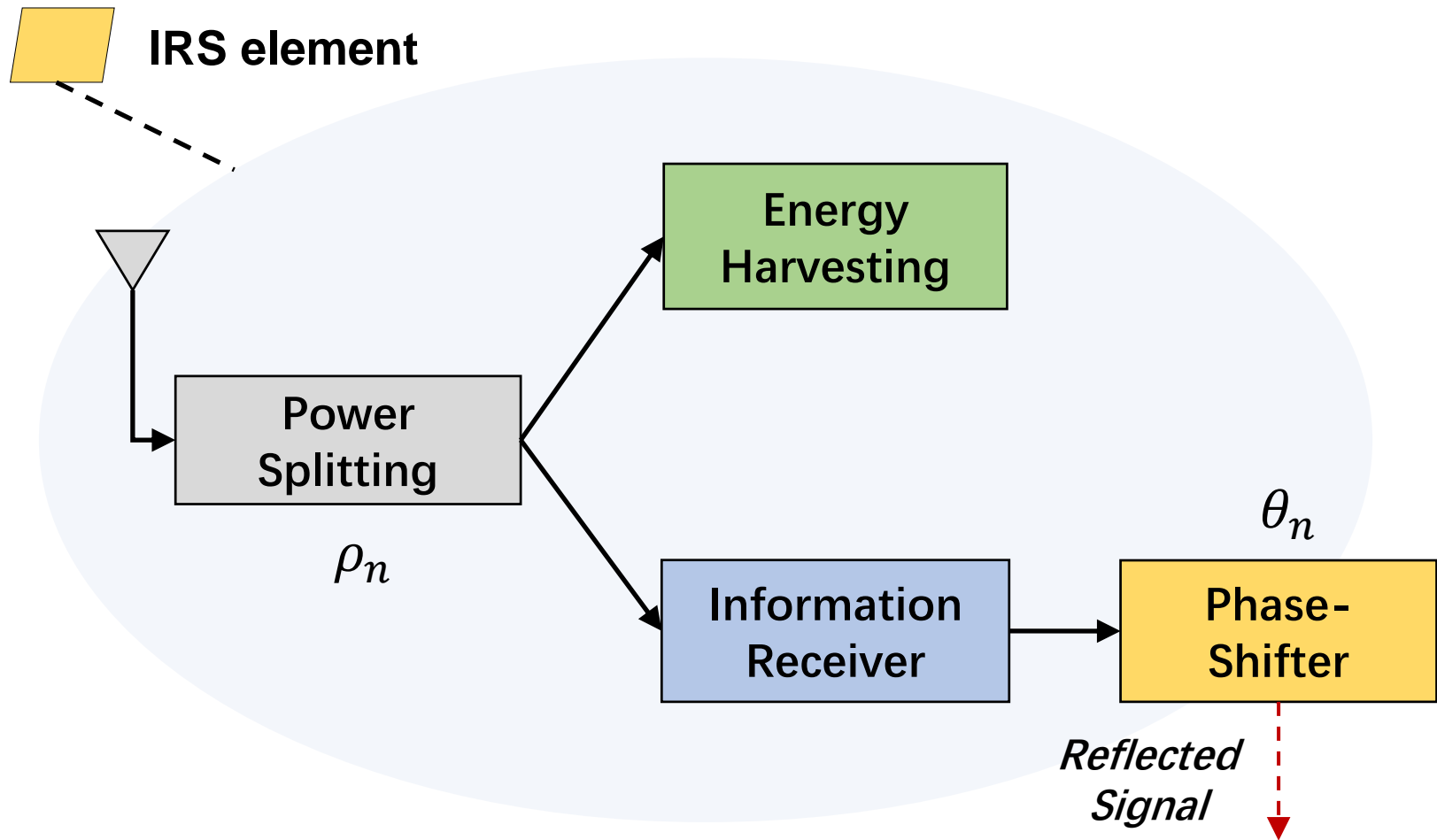
Introduction



Introduction



Introduction



System Model

- Channel Enhancement

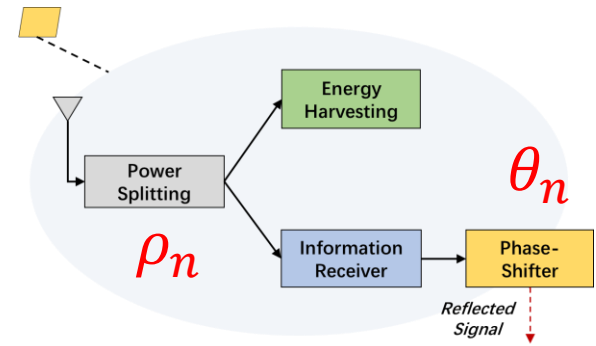
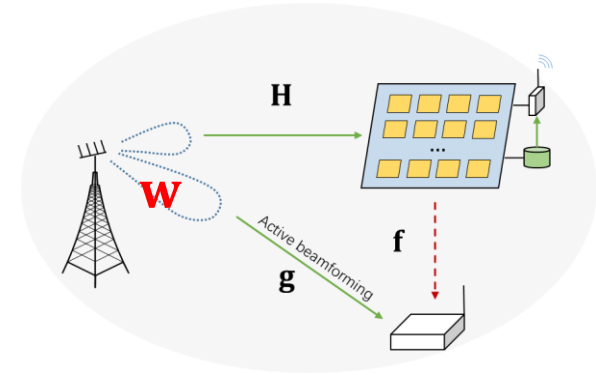
Enhanced Channel

$$\hat{\mathbf{g}} = \mathbf{g} + \mathbf{H}\Theta\mathbf{f}$$

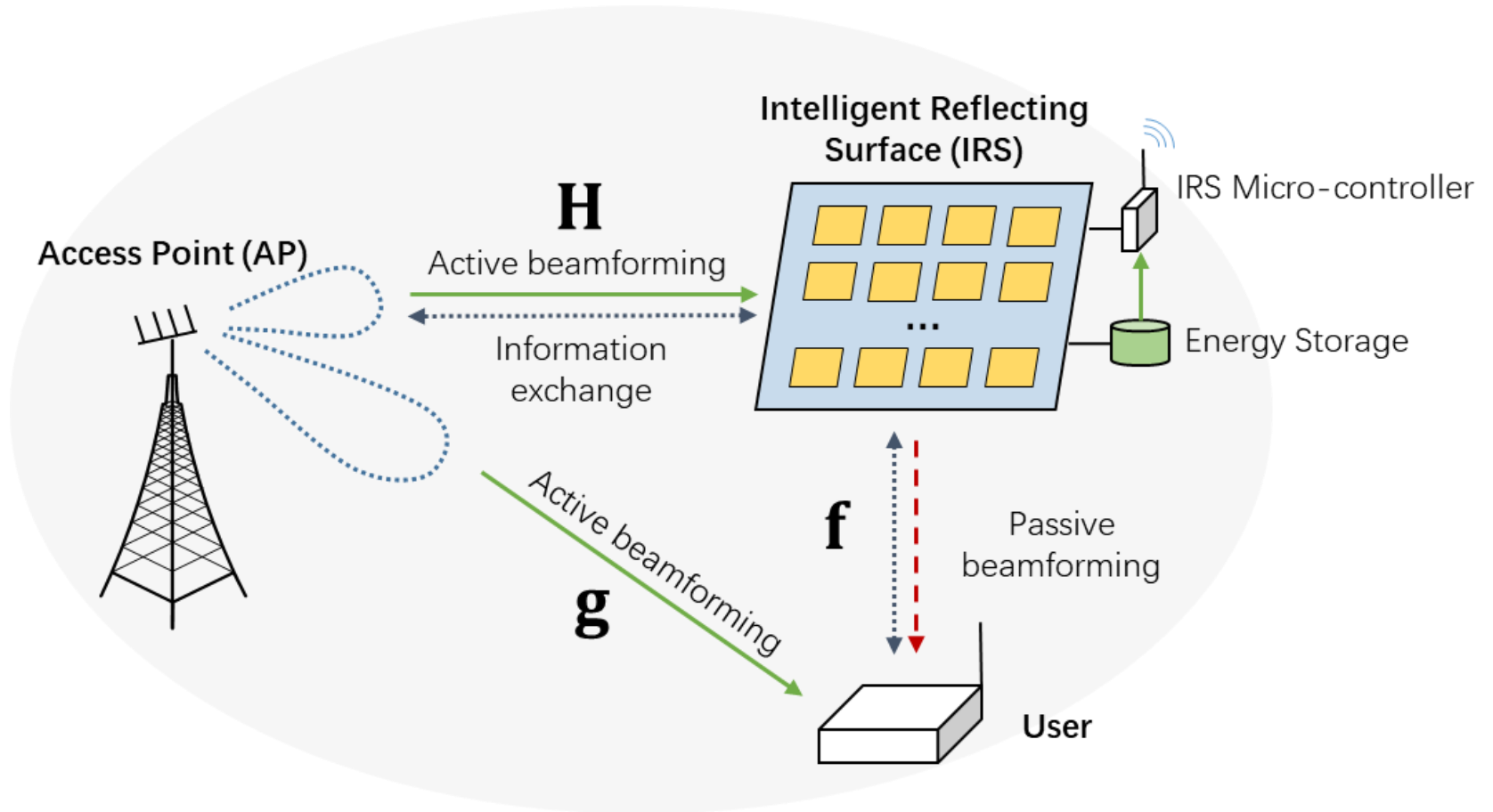
$$\Theta = \begin{bmatrix} \rho_1 e^{j\theta_1} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \rho_N e^{j\theta_N} \end{bmatrix}$$

Enhanced SNR

$$\gamma = \|\hat{\mathbf{g}}^H \mathbf{w}\|^2 / \sigma^2$$



System Model



System Model

- Self-sustainable IRS

Incident Signal
at element n

$$x_n = \mathbf{H}_n^H \mathbf{w}$$

Harvested
Energy

$$\eta \sum_{n=1}^N (1 - \rho_n^2) \|\mathbf{H}_n^H \mathbf{w}\|^2$$

Energy Budget

$$\eta \sum_{n=1}^N (1 - \rho_n^2) \|\mathbf{H}_n^H \mathbf{w}\|^2 \geq N\mu$$

System Model

Non-Convex | Highly Coupled

$$\max_{\mathbf{w}, \theta, \rho} \|(\mathbf{g} + \mathbf{H}\Theta\mathbf{f})^H \mathbf{w}\|^2$$

User SNR
Maximization

$$\text{s. t. } \|\mathbf{w}\|^2 \leq \bar{p}$$

Power Constraint

$$\eta \sum_{n=1}^N (1 - \rho_n^2) \|\mathbf{H}_n^H \mathbf{w}\|^2 \geq N\mu$$

Energy Constraint

Two-stage Approximation Algorithm

- Simplification and reformulation

$$\max_{\mathbf{w}, \theta, \rho} \left\| (\mathbf{g} + \bar{\rho} \mathbf{H} \hat{\Theta} \mathbf{f})^H \mathbf{w} \right\|^2$$

$$\text{s. t. } \|\mathbf{w}\|^2 \leq \bar{p}$$

$$\eta(1 - \bar{\rho}^2) \|\mathbf{H}^H \mathbf{w}\|^2 \geq N\mu$$

Identical PS ratio

Proposition 1. [Necessary cond.] AP-IRS-user link aligns with the direct link, i.e., AP- user link

$$\mathbf{H} \hat{\Theta} \mathbf{f} = \Delta \mathbf{g}$$

Two-stage Approximation Algorithm

- 1st Stage: Bisection

Algorithm 1 1st Stage: Bisection search

1) Initialize with feasible upper boundary of Δ , i.e., Δ_{\max} and $\Delta_L \leftarrow 0$, $\Delta_U \leftarrow \Delta_{\max}$, $\epsilon \leftarrow 10^{-5}$

2) **while** $\Delta_U - \Delta_L > \epsilon$:

$$\Delta_M = (\Delta_U + \Delta_L)/2$$

if Δ_M such that (6) is solvable **then**

$$\Delta_L \leftarrow \Delta_M, \Delta^* \leftarrow \Delta_M$$

else

$$\Delta_U \leftarrow \Delta_M$$

end if

end while

3) **Output:** Δ^*

Two-stage Approximation Algorithm

- 2nd Stage: Successive Convex Approx.

$$\max_{\mathbf{W}, \bar{\rho}} (1 + \bar{\rho} \Delta^*)^2 \mathbf{Tr}(\mathbf{G}\mathbf{W})$$

Non-Convex

$$\text{s. t. } \mathbf{Tr}(\mathbf{W}) \leq \bar{p}$$

$$\eta(1 - \bar{\rho}^2) \mathbf{Tr}(\hat{\mathbf{H}}\mathbf{W}) \geq N\mu$$

$\mathbf{Tr}(\cdot)$: Trace of matrix

$$\mathbf{G} = \mathbf{g}\mathbf{g}^H, \hat{\mathbf{H}} = \mathbf{H}\mathbf{H}^H$$

Successive Convex Approx.

Two-stage Approximation Algorithm

- 2nd Stage: Successive Convex Approx.

$$\gamma^{(k)} \triangleq \max_{\mathbf{W}, z} [(u^{(k)} + v^{(k)})^2 + 2(u^{(k)} + v^{(k)})(u$$
 (11a)

$$-u^{(k)} + v - v^{(k)}) - (u - v)^2]/4,$$

$$\text{s.t. } \text{Tr}(\mathbf{W}) \leq \bar{p},$$
 (11b)

$$\begin{bmatrix} 1 - z & \sqrt{\frac{N\mu}{\eta}} \\ \sqrt{\frac{N\mu}{\eta}} & \text{Tr}(\hat{\mathbf{H}}\mathbf{W}) \end{bmatrix} \succeq 0,$$
 (11c)

$$u \leq 2t^{(k)}(t - t^{(k)}) + [t^{(k)}]^2,$$
 (11d)

$$t \leq 1 + \Delta^* \sqrt{z},$$
 (11e)

$$v \leq \text{Tr}(\mathbf{G}\mathbf{W}),$$
 (11f)

Two-stage Approximation Algorithm

- 2nd Stage: Successive Convex Approx.

Algorithm 2 2nd stage: Successive Convex Approx.

With given Δ^* solved in the 1st stage, $\epsilon \leftarrow 10^{-5}$

Initialize $(\mathbf{W}, \bar{\rho})$ randomly that is feasible for problem (8)

Set $t^0 \leftarrow 1 + \Delta^* \bar{\rho}$, $u^0 \leftarrow (t^0)^2$, $v^0 \leftarrow \text{Tr}(\mathbf{G}\mathbf{W})$

while $\gamma^{(k)} - \gamma^{(k-1)} \geq \epsilon$

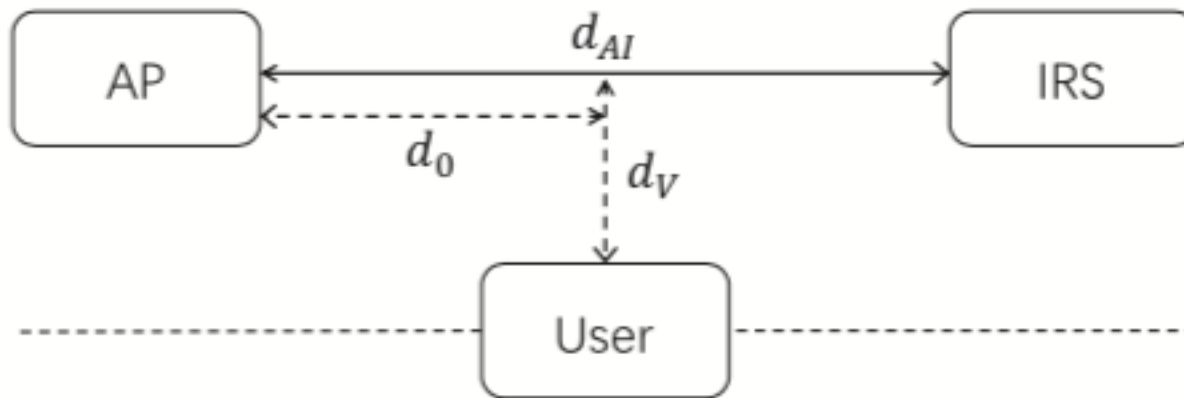
$\gamma^{(k)} \leftarrow \gamma^{(k-1)}$, $k \leftarrow k + 1$

$t^{(k)} \leftarrow t^{(k-1)}$, $u^{(k)} \leftarrow u^{(k-1)}$, $v^{(k)} \leftarrow v^{(k-1)}$

 Update $(\mathbf{W}, z, \gamma^{(k)}, t^{(k)}, u^{(k)}, v^{(k)})$ by solving (11)

end while

Numerical Results



Path Loss: $L = 30 + 20 \log_{10}(d)$

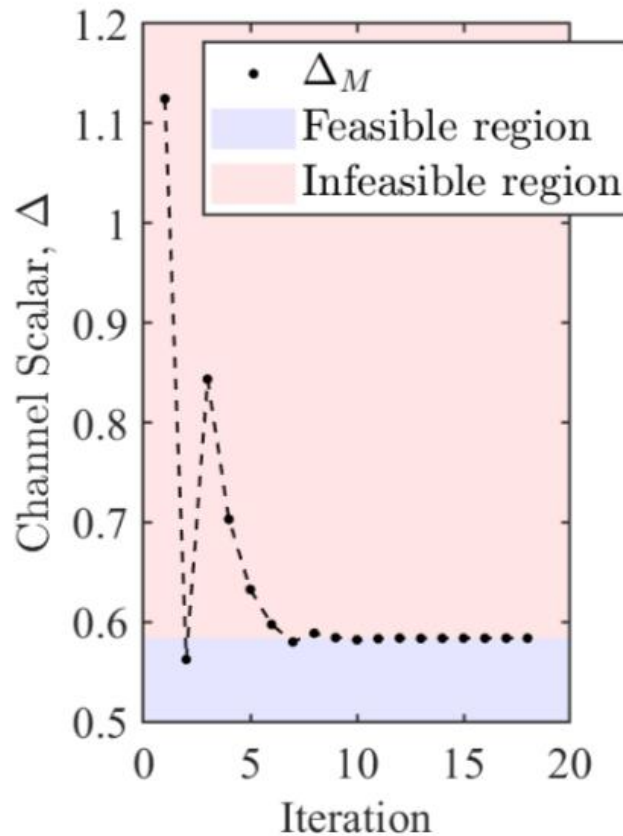
$M = 10, N = 80$

Energy harvesting efficient: $\eta = 0.8$

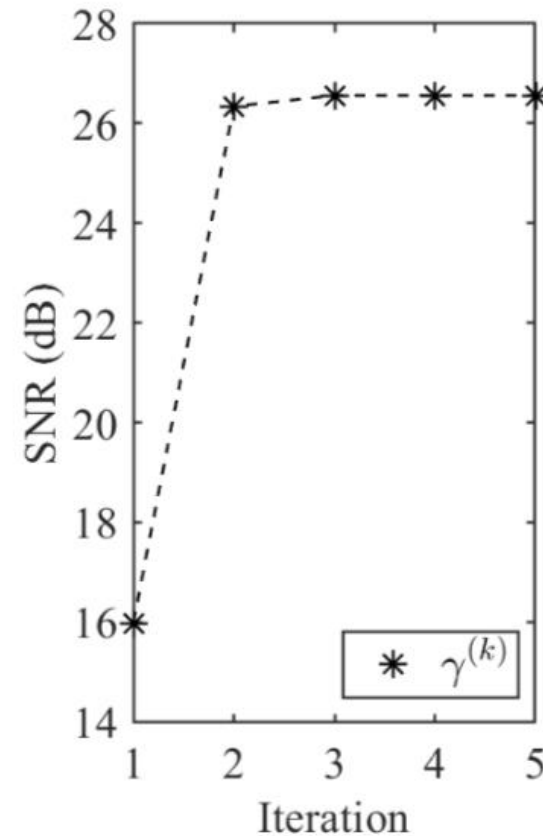
HAP Transmit Power:

$\bar{p} = 5$ dBm

Numerical Results



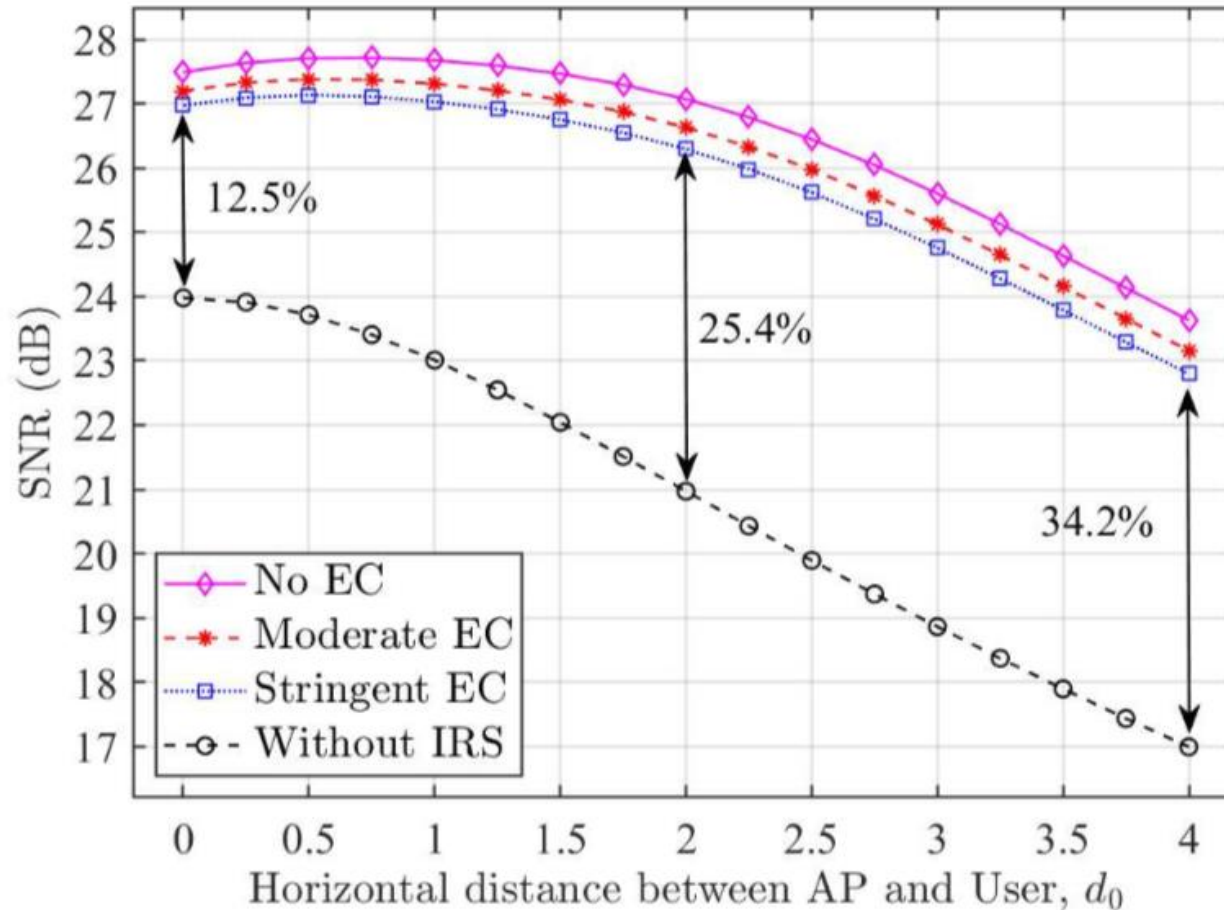
(a) 1st stage: Bisection



(b) 2nd stage: SCA

Verification of the two-stage algorithm convergence

Numerical Results



IRS-enhanced SNR against direct link quality under different IRS power consumption coefficients

Conclusions

- ✓ We formulate a throughput maximization problem that jointly we investigate the optimization of downlink SNR of the wireless powered intelligent reflecting surface-enhanced MISO system.
- ✓ To tackle the non-convexity, we propose a two-stage approximation algorithm by exploiting the structure of the problem.
- ✓ The extensive numerical results show that the influence of IRS power consumption on SNR improvement, and the feasibility of solving the IRS phase-shift independently by bisection algorithm with low complexity is also proved.

Questions & Answers

Thank you !

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